Efficient Noise Estimation With MUBs

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Outline

- Noise in Quantum Computation
- Figure of Merit for Implementations
- Estimating the Average Gate Fidelity
- Mutually-Unbiased Bases
- Efficient Noise Estimation with MUBs

Quantum Algorithms



Noise in Quantum Computation

- Goal: Compute U| ψ i perfectly for some algorithm U and starting state | ψ i 2 C^d
- Actual: Noisy implementation that introduces phase errors, bit flips, and decoherence. Have mixed states, i.e. we need density operators.



Think of noise as unitary operation in larger system followed by tracing out over the environment.



General Quantum Maps

|ψihψ|

An actual implementation of U is a quantum map E:

- Linear
- Trace-preserving or decreasing
- Completely positive
- Acts on density operators rather than states

Can decompose E using Kraus operators to describe noisy U:

$$E \widehat{A} i h \widehat{A} j \odot \square$$

$$A_k j \widehat{A} i h \widehat{A} j A_k \square$$

$$K \square$$

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Figure of Merit for Implementations

How good does an implementation of U work?



How well does a quantum channel transmit information?



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Fidelity as a distance measure between density operators:

 $F(\rho, \sigma) = tr(\rho \sigma^y)$ $F(\rho, \sigma) = tr (\rho^{1/2} \sigma \rho^{1/2})^{1/2}$

Will use this one, but makes no big difference.

For a quantum channel or a noisy implementation E, we have

 $\begin{array}{ll} F(U|\psi ih\psi|U^y,\,E(|\psi ih\psi|)) &= h\psi|U^y\,E(|\psi ih\psi|)\,\,U|\psi i\\ &= 1 \,\,\text{if}\,\,E = I,\,\text{otherwise less than}\,\,1 \end{array}$

Will write $F(U, \{E_k\})$ instead.

Minimum and Average Fidelity

Minimum Fidelity:

 $\mathsf{F}_{\mathsf{min}} = \mathsf{min}_{\psi} \mathsf{F}(\mathsf{U}, \{\mathsf{E}_{\mathsf{k}}\})$

Average Fidelity:

$$\begin{aligned} \mathsf{F}_{\mathsf{avg}} &= \mathsf{s} \; \mathsf{F}(\mathsf{U}, \{\mathsf{E}_k\}) \; \mathsf{d} \psi & \mathsf{us} \\ &= \mathsf{s} \; \mathsf{h} \psi | \mathsf{U}^\mathsf{y} \; \mathsf{E}(|\psi \mathsf{i} \mathsf{h} \psi|) \; \mathsf{U} | \psi \mathsf{i} \; \mathsf{d} \psi & \mathsf{or} \end{aligned}$$

using the unitarily invariant measure on C^d

How to measure F_{avg} ?

- Quantum Process/State Tomography to get the E_k; costly (see Nielsen, 2002 – quant-ph/0205035)

Estimating the Average Fidelity

Naive approach: Generate random states using random circuits V.



 $p_0 = F_{avg}$ if noise of U and U^y does not cancel out and noise introduced by V, V^y is neglibible compared to noise in U

Estimating the Average Fidelity

Works as well for Quantum Channels:



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Estimating the Average Fidelity



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Problem: Generating the V's is costly, of order 2ⁿ gates for most V needed.

- Solutions: 1. Efficient Random Circuits (see Emerson, Alicki, Zyczkowski 2005 – quant-ph/0503243)
 - 2. Random Sampling over subset of C^d



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- Mutually-Unbiased Bases
- MUBs for Efficient Noise Estimation

Mutually-Unbiases Bases (MUB)

An orthonormal basis B for C^d: B = { ψ_1 , ..., ψ_d }

Can we find other orthonormal bases that are orthogonal to B? No.

Can we find orthonormal bases that are almost orthogonal to B? Yes.

To orthonormal bases
$$B_1$$
, B_2 are called mutually-unbiased iff vectors from different bases have overlap 1/d.
jhÃj' ij $\mathbf{P} = \frac{1}{d}$

- Why MUBs? 1. State determination requires measurement wrt d+1 MUBs. (Schwinger, 1960; Ivanovic, 1981)
 - 2. The BB84 Protocol makes use of MUBs.

Existence of MUBs

For prime d, there is a set of d+1 mutually-unbiased bases. (Klappenecker and Rötteler, 2003 – quant-ph/0309120)

For non-prime d, there are at most d+1 mutually-unbiased bases. (Wootters and Fields, 1989)

For $d = p_1^{\alpha_1} \notin \varphi \notin p_k^{\alpha_k}$, there exist min_i (p_i + 1) MUBs.

Open Problems:

- How many MUBs exist in C⁶? (Only trivial lower bound of 3 known so far.)
- 2. How many MUBs exist for general non-prime dimension d?

An Example



The 3 MUBs for a single qubit state.

Construction of MUBs for prime powers d

See Klappenecker & Rötteler, 2003 (quant-ph/0309120).

Denote B_a the a-th basis, and let $B_a = \{|\psi^a_1 i, ..., |\psi^a_d i\}$. Let b denote the index of a vector in such a basis. Clearly a 2 {0, 1, ..., d}, and b 2 {1, ..., d}.

For odd prime powers d:
$$j\tilde{A}_{b}^{a}i \blacksquare p = \overset{\checkmark}{d} \overset{\times d}{\underset{x \blacksquare}{}^{f}} \overset{\ast}{\underset{d}{}^{f}} \overset{\ast}{\underset{d}{}} \overset{\ast}{\underset{d}{}}$$

Using finite field arithmetic to compute the trace.

For d = 2ⁿ:

$$j\tilde{A}_b^a i \square p = X ! \qquad I = D \qquad J x i$$

 $d_{x2T_n} \neq e^{2\pi i/4}$

Using Galois ring arithmetic to compute the trace.

These d bases and the computational basis give d+1 MUBs.

Efficient Noise Estimation



Where V is a circuit that randomly generates an MUB vector $|\psi^a_{\ b}i$.

$$F_{\text{avg}} = \int \langle \psi | U^{\dagger} \mathcal{E}(|\psi\rangle \langle \psi|) U | \psi\rangle d | \psi\rangle = \frac{\sum_{k} |\operatorname{tr} E_{k}|^{2} + d}{d^{2} + d}$$
(Horodecki et al., PRA, 1999)

We showed that

$$\frac{1}{d^2 + d} \sum_{a=0}^{d} \sum_{b=1}^{d} \langle \psi | U^{\dagger} \mathcal{E}(|\psi\rangle \langle \psi|) U | \psi\rangle = \frac{\sum_{k} |\operatorname{tr} E_{k}|^{2} + d}{d^{2} + d}$$
$$\implies \text{ "Cheap" average using MUBs is sufficient!}$$

Proof (sketch)

Lemma 1: Let W be the subspace of all Hermitian traceless linear operators and let

$$W_{a} = \left\{ \sum_{b=0}^{d-1} r_{b} |\psi_{b}^{a}\rangle \langle \psi_{b}^{a}| : \sum_{b=1}^{d} r_{b} = 0 \right\}.$$

Then $W = \bigoplus_{a=0}^{d} W_a$.

Lemma 2: The operators

$$\Pi_a(V) = \sum_{b=1}^d |\psi_b^a\rangle \langle \psi_b^a | V | \psi_b^a \rangle \langle \psi_b^a |$$

on W form a complete set of orthogonal projectors on W.

Corollary 3: For $M, N \in W$,

$$\sum_{a=0}^{d} \operatorname{tr} \left(\Pi_{a}(M) \Pi_{a}(N) \right) = \operatorname{tr} MN.$$
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Proof sketch (cont'd)

We can extend Theorem 4 to non-traceless Hermitian operators via the trick $\widetilde{M} = M - \frac{\operatorname{tr} M}{d} \mathbb{1}, \widetilde{N} = N - \frac{\operatorname{tr} N}{d} \mathbb{1}$

$$x^{d} x^{d}$$

 $h\tilde{A}_{b}^{a}jMj\tilde{A}_{b}^{a}ih\tilde{A}_{b}^{a}jNj\tilde{A}_{b}^{a}i \blacksquare \blacksquare \blacksquare N \blacksquare \blacksquare \blacksquare$

Using another trick, we can extend this to general linear operators:

$$\mathsf{M} \supseteq \mathsf{M} \cong \mathsf{M}^{\mathsf{y}}; \mathsf{M} \supseteq \mathsf{G}^{\mathsf{i}} \mathsf{i}^{\mathsf{y}} \mathsf{M}^{\mathsf{i}} \mathsf{G}^{\mathsf{i}} \mathsf{N}^{\mathsf{y}} \mathfrak{D} \mathsf{N} \supseteq \mathsf{G}^{\mathsf{i}} \mathsf{N}^{\mathsf{y}}; \mathsf{N} \supseteq \mathsf{G}^{\mathsf{i}} \mathsf{i}^{\mathsf{i}} \mathfrak{M}^{\mathsf{i}} \mathsf{I}^{\mathsf{y}} \mathfrak{D}^{\mathsf{i}} \mathsf{I}^{\mathsf{i}} \mathsf{I}^{\mathsf{i}$$

Summing over all four combinations of these, we get Corollary 5 for all linear operators.

Proof sketch (finished)

by using the last result and expanding E.

Summary

- Noise in Quantum Algorithms
- Figures of Merit
- Mutually-Unbiased Bases
- Noise Estimation works well with MUBs